

Deutsche Telekom Chair of Communication Networks

Joint usage of 802.11p and LTE-V2V for reliable control of heterogeneous vehicle platoon

Oleksandr Zhdanenko Dresden, 17. July 2018

Outline

- Introduction and Motivation
- Platoon management
- Communication solutions (LTE-V2V and 802.11p)
- Research plans and Testbed
- Conclusions





Introduction

- Platooning
 - Safety improvement
 - Traffic flow efficiency improvement

- Cost saving
- CO2 emission reduction



[1]

[1] https://phys.org/news/2017-11-highway-youtruck-platooning.html



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Page 3



Motivation

- Platooning requirements:
 - Low latency communication
 - 10 100 ms depending on the message type [2] [3]
 - Network resilience (99.999%) [3]

- Requirements achievable
 - To ensure resilience and low latency by
 - Vehicle-to-Vehicle (V2V) communication
 - Vehicle-to-Infrastructure (V2I) communication

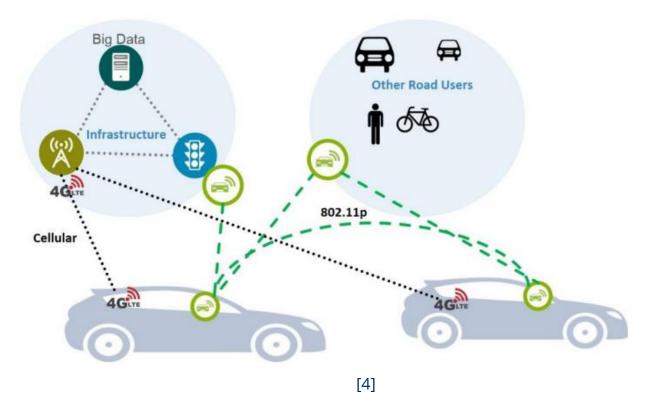
[2] ETSI TS 102 637-2 V1.2.1[3] Radio Resource Management for D2D-Based V2V Communication. Wanlu Sun, Erik G. Ström, Fredrik Brännström, Member, and Yutao Sui





Motivation

- Intelligent Transportation Systems (ITS) typically use:
 - LTE-V2V
 - 802.11p
- Heterogeneous usage of both technologies
 - To improve reliability
 - To provide ubiquities connectivity



[4] Ready to roll: Why 802.11p beats LTE and 5G for V2X. Alessio Filippi, Kees Moerman, Gerardo Daalderop, Paul D. Alexander, Franz Schober, and Werner Pfliegl



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Page 5



Protocol structure

Application: Platoon management

Facility: Cooperative Awareness Messages

Transport and Network: GeoNetworking and LTE-V2V or 802.11p







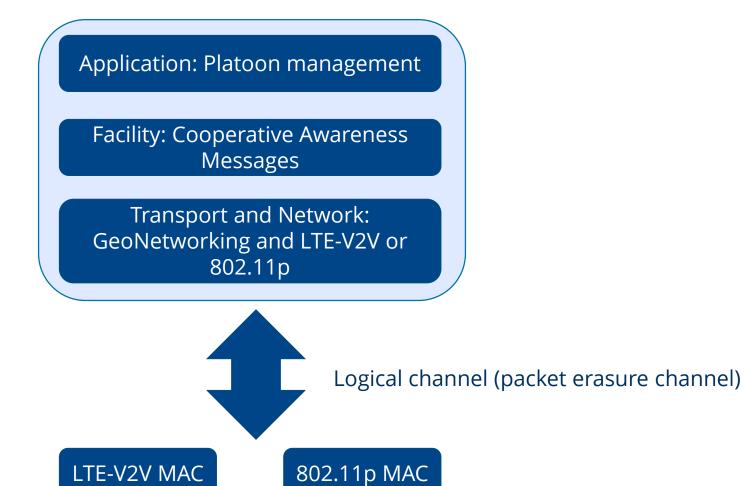
Platoon management, CAM and GeoNetworking







Platoon management

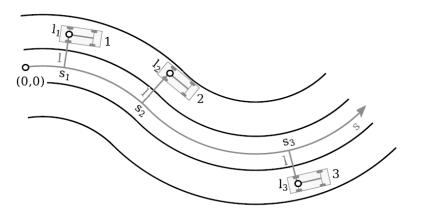


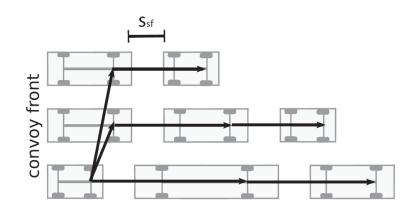
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Distributed graph-based platoon control

- Supports multilane platoons of heterogeneous vehicles
- Uses Longitudinal and Lateral Controllers to manage the convoy [6]
- The data to be shared over Cooperative Awareness Messages (CAM)
 - GPS coordinates
 - Vehicle velocity
 - Length of the vehicle
 - ...
- Graphs calculated locally, based on received CAMs
- State is shared only with the neighbouring cars
- GeoNetworking could be used for messages dissemination





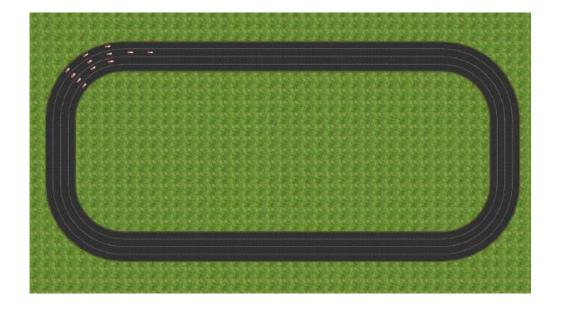
[6] Distributed Graph-Based Control of Convoys of Heterogeneous Vehicles using Curvilinear Road CoordinatesV2X. I[~]naki Navarro, Florian Zimmermann, Milos Vasic, Alcherio Martinoli

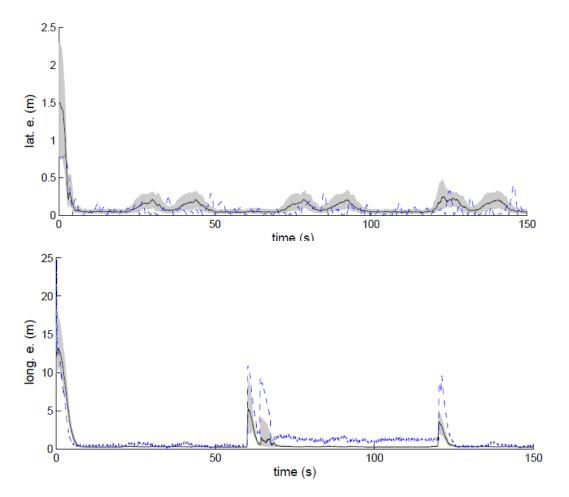




Distributed graph-based platoon control

- Curvature zones cause bigger lateral errors [6]
 Lane change operation causes bigger longitudinal error
- Simulation speed ~ 10 m/s





[6] Distributed Graph-Based Control of Convoys of Heterogeneous Vehicles using Curvilinear Road CoordinatesV2X. I~naki Navarro, Florian Zimmermann, Milos Vasic, Alcherio Martinoli



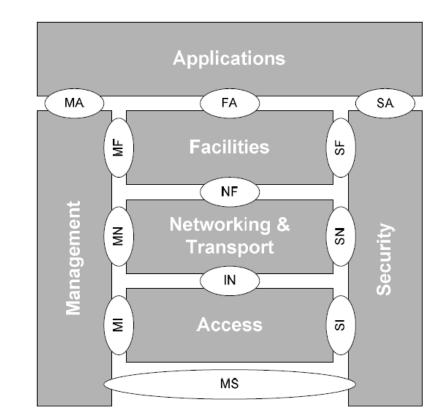
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Page 10



Intelligent Transportation System

- Standardized by ETSI EN 302 665
- Essential aspects [8]
 - Stations mobility and high dynamics of its topology
 - Potential support of multiple communication technologies
 - Multiple physical units in a single ITS-S
 - Prioritization of application classes
 - Unified format of awareness messages (CAM)



ITS Stations (ITS-S) architecture

[8] ETSI EN 302 665 V1.1.1





Cooperative Awareness Message (CAM)

- Contains status and attribute information of the originating ITS-S [9]
 - Status information includes time, position, motion state, activated systems, etc.
 - Attribute information includes data about the dimensions, vehicle type and role in the road traffic, etc.
- Max messages frequency = 10 Hz (T = 100 ms)
- Min messages frequency = 1 Hz (T = 1000 ms)
- Message size = 800 bytes [2]
- High Frequency (HF) container
 - Contains all fast-changing (dynamic) status information
- Low Frequency (LF) container
 - Contains Static or slow-changing vehicle data

| САМ | | | | |
|----------------|--------------------|--|---|--|
| ITS PDU header | Basic Container | HF Container Vehicle HF Container or Other containers | LF Container (Conditional) Vehicle LF Container or Other containers (not yet defined) | Special vehicle Container (Conditional) Public Transport Container or Special Transport Container or |

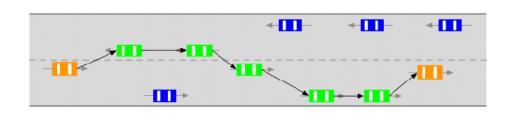
[2] ETSI TS 102 637-2 V1.2.1 [9] ETSI EN 302 637-2 V1.3.2



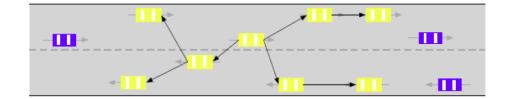
GeoNetworking

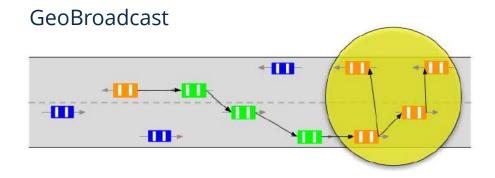
GeoUnicast

- Ad hoc networking based on geographical addressing and routing [7]
 - Every node has a partial view of the network topology in its vicinity
 - Every packet carries a geographical address
- Supports point-to-point and point-to-multipoint communication



GeoAnycast





[7] ETSI EN 302 636-1 V1.2.1





LTE-V2V and 802.11p



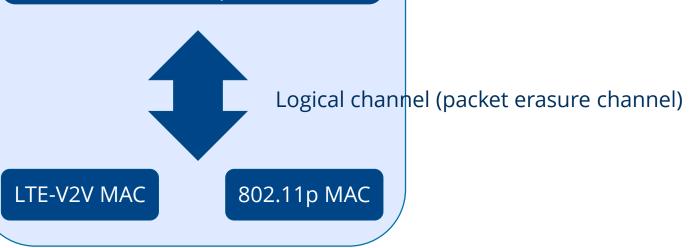


LTE-V2V and 802.11p

Application: Platoon management

Facility: Cooperative Awareness Messages

Transport and Network: GeoNetworking and LTE-V2V or 802.11p



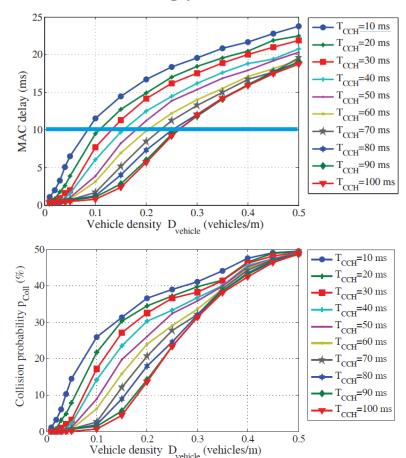




802.11p CSMA / CA

- Current standard for V2V communications
- Support of variable packet sizes
- Requires no strict synchronization between
 nodes

- Unbounded delays before channel access
- Collisions on the channel
- Multiple consecutive packet drops
- Problems with predictability for periodic positioning messages



Tccн – Sending period [10]

[10] Performance Evaluation of IEEE 802.11p MAC Protocol in VANETs Safety Applications. Lusheng Miao, Karim Djouani, Barend Jacobus Van Wyk, Yskandar Hamam



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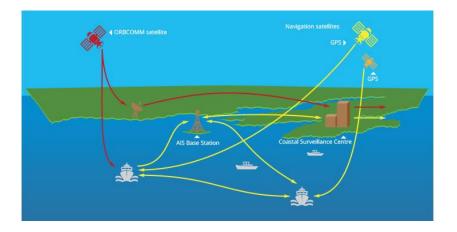
Page 16

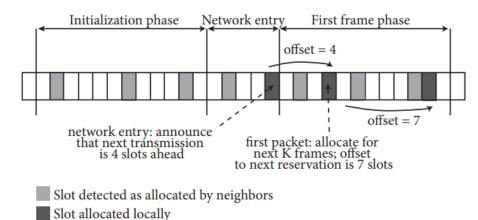


802.11p Self-organizing TDMA (STDMA)

- Is already in commercial use in automatic identification system (AIS) [11]
- Predictable channel access delay
- Good scalability

- **Initialization:** Listen to the channel activity during 1 frame
- **Network entry:** Select the free time slot or the slot used by the station located furthest away
- First Frame: Reserve the slot
- **Continuous operation:** Periodically transmit messages [12]





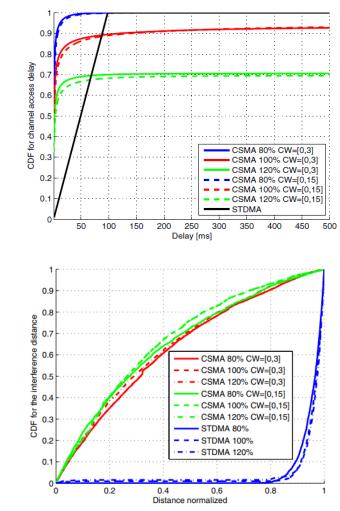
[11] On the Ability of the 802.11p MAC Method and STDMA to Support Real-Time Vehicle-to-Vehicle Communication. Katrin Bilstrup, Elisabeth Uhlemann, ErikG Ström, Urban Bilstrup [12] In-depth Analysis and Evaluation of Self-Organizing TDMA. Tristan Gaugel, Jens Mittag, Hannes Hartenstein, Stylianos Papanastasiou[†], Erik G. Stroem



802.11p Self-organizing TDMA (STDMA)

- Requires slot synchronization and position information
- STDMA outperforms CSMA / CA with growing number of the vehicles

- Evaluation performed for [13]
 - Frequency = 2 Hz
 - Packet size = 800 byte
 - Communication range = 1000m

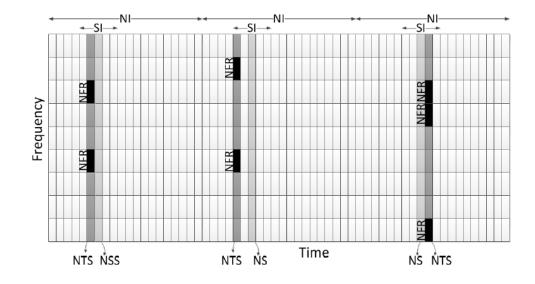


[13] Scalability Issues of the MAC Methods STDMA and CSMA of IEEE 802.11p When Used in VANETs. Katrin Sjöberg-Bilstrup, Elisabeth Uhlemann[†], Erik G. Ström

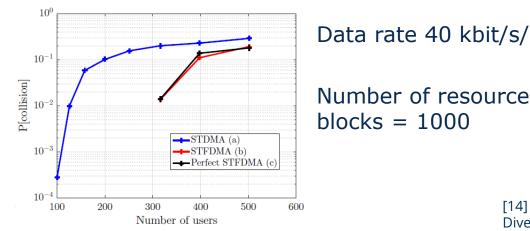


802.11p Self-organizing TFDMA (STFDMA)

- Resource block are split by time slots and frequency sub-٠ carriers [14]
- Can handle more simultaneous transmissions •



Outperforms STDMA, but no deep ٠ evaluation has been done yet



Data rate 40 kbit/s/user

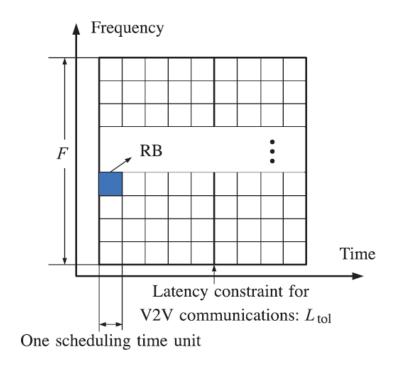
[14] STFDMA: A Novel Technique for Ad-Hoc V2V Networks Exploiting Radio Channels Frequency Diversity. M. A. Gutierrez-Estevez, D. Gozalvez-Serranoy, M. Botsovy, S. Sta nczak





LTE-V2V

- Performs centralized Radio Resource Management for D2D communications [15]
 - Underlay
 - Overlay
 - Managed Mode
 - Unmanaged mode
- V2V services have stringent latency and reliability requirements
- Cellular traffic on the other hand aims at maximizing the sum throughput under certain fairness considerations [3]



[3] Radio Resource Management for D2D-Based V2V Communication. Wanlu Sun, Erik G. Ström, Fredrik Brännström, Member, and Yutao Sui [15] 5G D2D Networks: Techniques, Challenges, and Future Prospects. Rafay Iqbal Ansari, Chrysostomos Chrysostomou, Syed Ali Hassan, Mohsen Guizani, Shahid Mumtaz, Jonathan Rodriguez, Joel J. P. C. Rodrigues



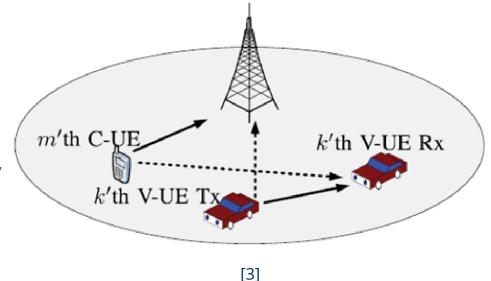
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Page 20



LTE-V2V

- Drawbacks
 - Interference with Cellular-UEs
 - Computational overhead for Radio Resource
 Management
 - Required channel state information is not always available, especially for vehicle ITS with high mobility
 - Current infrastructure doesn't cover all roads
 - Malfunction of the Base station will cause problems in vehicular safety systems in its range



 [3] Radio Resource Management for D2D-Based V2V Communication. Wanlu Sun, Erik G. Ström, Fredrik Brännström, Member, and Yutao Sui
 [16] Performance Analysis of V2V Beaconing Using LTE in Direct Mode with Full Duplex Radios. Alessandro Bazzi, Barbara M. Masini, Alberto Zanella



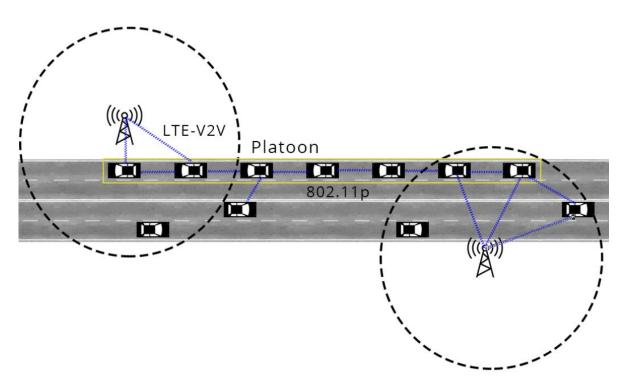
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Page 21

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Joint usage of 802.11p and LTE-V2V

- Balance between LTE-V2V Managed mode and 802.11p when sender and receiver are in the LTE coverage area
- Use LTE-V2V Unmanaged mode and 802.11p for out of cell communication
- Switch between CSMA/CA and STDMA/SFTDMA depending on the number of vehicles in range for 802.11p







Adaptive platoon management framework

- Based on Channel State Information of LTE-V2V and 802.11p
 - Select appropriate way to transfer messages
 - Use both ways if higher reliability should be achieved
 - Collision warning
 - Public safety messages
 - Adapt platoon parameters based on the channel quality
 - Speed
 - Distance between vehicles
 - CAM sending period
 - Predict Quality of Service











Testbed

- Simulation of realistic highway traffic system
- Test emergency scenarios with different network parameters
 - 802.11p CSMA / CA
 - 802.11p STDMA
 - 802.11p STFDMA
 - LTE-V2V mode 3
 - LTE V2V mode 4
 - Joint usage of 802.11p and LTE-V2V
- Heterogeneous platoon members
- Static and adaptive platoon parameters mode





Conclusions

- To guarantee delay constraints 802.11p should implement alternative MAC protocol for high network loads
- Managed LTE-V2V alone could not be sufficient for platoon management in dense traffic scenarios
- Channel bonding of 802.11p and LTE-V2V should be considered
- Use Testbed for joint modelling of communication solutions and platoon management





Thank you!



